

ERRATA: Airplane Flight Dynamics and Automatic Flight Controls Part I

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- page 28, Line 9* “un” should be in.
- page 40, Line 26* Should read, “ apply to cambered (un-symmetrical) airfoils.”
- page 59, Figure 2.20* Flap Chord, c_f , should go from hinge line to trailing edge
- page 66, Figure 3.2* β should be β_1 in Note 3.
- page 84, Eqn (3.30)* The wing incidence should be removed
- page 97, Figure 3.28* Normal velocity vector on left wing should not be present.
- page 99, Figure 3.30* Axis labeled as “Z” should be labeled as “X”.
- page 106, Eqn (3.67)* K_{SW} needs to be defined: is the gearing constant between cockpit control wheel or stick and aileron or spoiler deflection.
- page 111, Eqn (3.76)* Should read: $F_{A_{y_v}} = C_{y_{\beta_v}} \beta \bar{q} S = -C_{L_{\alpha_v}} \left(1 - \frac{d\sigma}{d\beta} \right) \beta \bar{q}_v S_v$
- page 115, Line 14* “The yawing moment due to the vertical tail me be written as:” should be “The yawing moment due to the vertical tail may be written as:”
- page 117, Line 20* Line 20 should be between Lines 13 and 14.
- page 118, Figure 3.46* “Positive rolling moment” should be labeled as “Yawing moment”.
- page 118, Figure 3.46, 1.)* “induces drag” should be “induced drag”
- page 122, Eqn 3.92a* The summation should say $i = 1$
- page 122, Eqn 3.92b* The summation should say $i = 1$

<i>page 122, Eqn 3.92c</i>	The summation should say $i = 1$
<i>page 124, Eqn 3.95b</i>	The summation should say $i = 1$
<i>page 126, Table 3.4</i>	“ V_1 ” should be “ Q_1 ”
<i>page 127, Line 4</i>	Should read, “(2) partial derivatives in Table 3.4 indicate the slope by which a particular perturbed force or moment is affected by a particular perturbed variable.”
<i>page 133, Figure 3.51</i>	All “ V_{P_i} ” in this figure should be “ V_p ”
<i>page 134, Figure 3.52</i>	Equation “ $\arctan \left. \frac{\partial C_D}{\partial M} \right _{M=M_2} > 0$ ” should be “ $\arctan \left. \frac{\partial C_D}{\partial M} \right _{M=M_2} < 0$ ”. Figure should be labeled “Example of Determination of: $\partial C_D / \partial M$ at a constant angle of attack”.
<i>page 136, Eqn (3.119)</i>	“ C_L ” should be “ C_{L_1} ”
<i>page 136, Eqn (3.122)</i>	Variable M should be “ M_A ”
<i>page 147, Eqn (3.162)</i>	“ $\frac{\alpha \bar{c}}{2U_1}$ ” should be “ $\frac{\dot{\alpha} \bar{c}}{2U_1}$ ”
<i>page 162, Eqn (3.197)</i>	“ C_{n_p} ” and “ C_{n_r} ” should be “ $C_{n_{p_1}}$ ” and “ $C_{n_{r_1}}$,” respectively.
<i>page 195, Line 6</i>	“Table 5.1” should be “Table 4.1”.
<i>page 196, Line 2</i>	“Table 5.1” should be “Table 4.1”.
<i>page 209, Fig 4.11b</i>	The negative tail stall locus as shown in the diagram is wrong. The trim diagram should have a positive tail stall locus at $\alpha = 25^\circ$ and a negative tail stall locus at $\alpha = -12^\circ$. Both of these lines are out of the range of the diagram so none of them should be shown.
<i>page 211, 11th line</i>	The sentence that reads, “Figure 4.11b shows only the negative tail stall locus because the positive locus is outside of the diagram” should be removed.
<i>page 225, Eqn (4.86b)</i>	“ C_{Y_r} ” should be “ C_{y_r} ”.

- page 227, Eqn (4.96)* “ C_{Y_r} ” should be “ C_{y_r} ”.
- page 227, Eqn (4.97)(4.103)* “ Φ ” should be “ Φ_1 ”
- page 227, Line 6* The first sentence should be removed
- page 228, Eqn (4.98)* Variables a_{11} , b_{11} , and c_{11} should be a, b, and c
- page 228, Eqn (4.99)* Variables a_{11} , b_{11} , and c_{11} should be a, b, and c
- page 228, Eqn (4.100)* Variables a_{11} , b_{11} , and c_{11} should be a, b, and c
- page 228, Eqn (4.102)* “ Φ ” should be “ Φ_1 ”
- page 228, Eqn (4.102a)* Variable a_{11} should be a.
- page 228, Eqn (4.102b)* Variable b_{11} should be b.
- page 228, Eqn (4.102c)* Variable c_{11} should be c.
- page 232, Eqn (4.113b)* “ γ_1 ” should be “ Θ_1 ”
- page 232, Eqn (4.114a)* “ γ_1 ” should be “ Θ_1 ”
- page 237, Lines 10-11* Should read: “From Eqn (4.133) it may be concluded that as long as L_h is positive (i.e. ‘up’) and $(x_{ac_{wf}} - x_{cg})$ is positive the canard load to trim, L_c , will also be positive (i.e. ‘up’).”
- page 259, Figure 4.36* In graph a) “ $\delta_e = 2^\circ$ ” should be “ $\delta_{t_e} = 2^\circ$ ”
- page 259, Figure 4.36* In graph b) “dFe/dV” should be “dFs/dV”
- page 263, Line 2* Second “the” should be removed.
- page 269, Eqn 4.199* “ $C_{n_{\beta_{fix}}} - C_{n_{\delta_r}}$ ” should be $C_{n_{\beta_{fix}}} + C_{n_{\delta_r}}$
- page 273, Line 4* “and (4.209)” should be removed.
- page 278, Line 6* HM should refer to Eqn (4.136).
- page 278, Eqn (4.225)* Equation # 4.225 is repeated for two different equations.

<i>page 278, Line 22</i>	Should read, “The hingemoment coefficient equation...”
<i>page 280, Line 15</i>	“ $\frac{\partial \delta_e}{\partial n}$ ” should be “ $\frac{\partial F_s}{\partial n}$ ”
<i>page 286, Eqn (4.241)</i>	$C_{h\beta_r}$ should be $C_{h\beta_v}$
<i>page 288, Line 2</i>	Sentence should read “Exceptions to this are airplanes like the B-52.”
<i>page 288, Line 14</i> <i>page 288-290</i>	Remove “!” after “nose-gear.” “ground” subscript should be “g”
<i>page 291, Eqn.(4.250)</i>	$\ddot{\theta}$ should be $\ddot{\theta}_{mg}$
<i>page 292, Figure 4.52b</i>	x_{cgg} labels should be reversed for $x_{cgg} = 38 \text{ ft}$ and $x_{cgg} = 39 \text{ ft}$
<i>page 314, Figure 5.6</i>	Solid black line needs removed.
<i>page 316, Line 9</i>	Line is “the system is zero” should be “the system are zero”
<i>page 324, Line 16</i>	Remove the list number “1)” and align row to far left.
<i>page 328, Eqn (5.48)</i>	“>” should be “<”
<i>page 328, Eqn (5.49)</i>	“>” should be “<”
<i>page 333, Line 8</i>	$T_1 = -0.35$ and $T_2 = 0.28$
<i>page 342, Eqn (5.82a)</i>	In equation, “ $\frac{2\zeta_p s}{\omega_{n_{sp}}}$ ” should be “ $\frac{2\zeta_p s}{\omega_{n_p}}$ ”
<i>page 342, Eqn (5.82b)</i>	In equation, “ $\frac{2\zeta_p s}{\omega_{n_{sp}}}$ ” should be “ $\frac{2\zeta_p s}{\omega_{n_p}}$ ” and “ $\frac{2\zeta_\alpha}{\omega_{n_\alpha}}$ ” should be “ $\frac{2\zeta_\alpha s}{\omega_{n_\alpha}}$ ”
<i>page 342, Eqn (5.82c)</i>	In equation, “ $\frac{2\zeta_p s}{\omega_{n_{sp}}}$ ” should be “ $\frac{2\zeta_p s}{\omega_{n_p}}$ ”
<i>page 350, Line 5</i>	“ $\phi(s) / \delta_e(s)$ ” should be “ $\phi(s) / \delta(s)$ ”
<i>page 364, Line 28</i>	Eqn (5.120) should be Eqn (5.121)

<i>page 381, Figure 5.24</i>	For Damping Ratio “-1/T” should be “1/T”
<i>page 381, Figure 5.25</i>	For Damping Ratio “-1/T” should be “1/T”
<i>page 396, Line 25</i>	Should read, “...say 10 deg/deg/sec, a 3 deg/s pitch rate...”
<i>page 398, Line 2</i>	“elevator deflection” should be “rudder deflection”
<i>page 401, Figure 5.44</i>	On the Y_B vector, the smaller vector should be labeled “q”
<i>page 405, Lines 24-28</i>	Omit paragraph contained by lines 24-28.
<i>page 407, Line 13</i>	$\cos \theta = 1$ for small angles.
<i>page 427, Line 6</i>	Remove the return so “be” and “written” are on the same line.
<i>page 427, Line 7</i>	“time to double” should be “time-to-double.”
<i>page 434, Line 12</i>	Reference 6.5 should be Reference 6.6.
<i>Appendix B</i>	$C_{h\beta_r}$ should be $C_{h\beta_v}$ for all examples.
<i>page 487, B2</i>	C.G. location should be $0.33 \bar{c}$